

## Diff Geo Lecture 2

Recall

- Given  $M$ , we can construct the tangent bundle  $TM$ , which comes equipped with a map  $\pi: TM \rightarrow M$  where  $\forall p \in M, \pi^{-1}(p) = T_p M$ . In addition, given coordinates  $x^i$  on  $M$ , we get coordinates on  $TM$  by  $(p, v) \mapsto (x^1(p), \dots, x^n(p), v^1, \dots, v^n)$  where  $v = v^i \partial_i$ .

A local section of  $TM$  is a map  $\sigma: U \rightarrow TM$  s.t.

$$\pi \circ \sigma = \text{id}_U$$

- Essentially assigning to each  $p \in U$  a vector  $v \in T_p M$

Def: A vector field on  $M$  is a global section

$X: M \rightarrow TM$ . We often denote  $X(p) = X_p \in T_p M$ , and the set of all vector fields as  $\mathfrak{X}(M)$ .

We already know local vector fields - given coords  $x^i$ , we have the coordinate vector fields  $\frac{\partial}{\partial x^i}$  where

$$\left. \frac{\partial}{\partial x^i} \right|_p = \frac{\partial}{\partial x^i} \Big|_p$$

We know that for all  $p \in U$ , the  $\frac{\partial}{\partial x^i}|_p$  form a basis  $\Rightarrow$  any smooth vector field  $X$

can be written locally as  $X^i \frac{\partial}{\partial x^i}$  for smooth functions  $X^i: U \rightarrow \mathbb{R}$  called the component functions

$\mathfrak{X}(M)$  has more structure - it is a vector space,  
(in fact, a  $C^\infty(M)$ -module)

given  $X \in \mathfrak{X}(M)$ ,  $fX$  is the vector field  
 $(fX)_p = f(p)X_p.$

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Recall that tangent vectors act on functions -  
they are derivations  $C^\infty(M) \rightarrow \mathbb{R}$ .

By acting pointwise, this means that vector fields  
act on  $C^\infty(M)$  as well.

Define  $Xf \in C^\infty(M)$  by

$$(Xf)(p) = X_p f \in \mathbb{R}$$

In this way, vector fields are derivations

i.e.  $X(fg) = fXg + gXf$

Note that when a function appears matters  
 $fX$  is a vector field,  $Xf$  is a function

As with our example w/ vectors/derivations on  $\mathbb{R}^n$ , there  
 is a bijection  $\{\text{vector fields}\} \leftrightarrow \{\text{derivations on } C^\infty(M)\}$   
 $X \mapsto D_x$  where  $D_x f = Xf$

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Smooth maps  $F$  and tangent vectors interact via  
 the derivative  $dF_p$ . The same applies to vector fields.

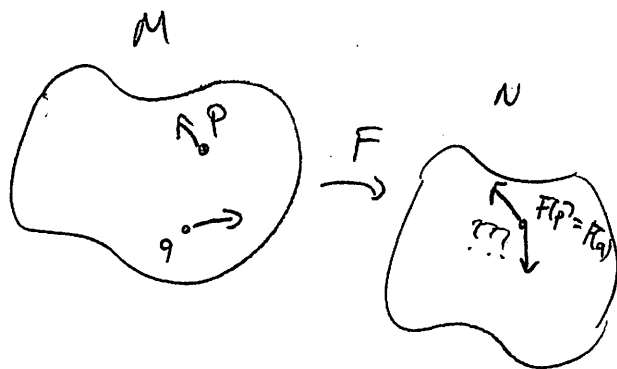
Given  $X \in \mathfrak{X}(M)$ ,  $F: M \rightarrow N$ , we want to define a  
 vector field  $Y$  on  $N$ .

The obvious thing -  $Y_p = dF_{F^{-1}(p)}(X_{F^{-1}(p)})$

Two problems

1)  $F^{-1}(p) = \emptyset$

2)  $|F^{-1}(p)| > 1$



Def: Given  $F: M \rightarrow N$ ,  $X \in \mathfrak{X}(M)$  and  $Y \in \mathfrak{X}(N)$   
 are F-related if  $\forall p \in M$ ,

$$dF_p(X_p) = Y_{F(p)}$$

In the case that  $F$  is a diffeomorphism, there  
 is a unique such vector field, denoted

$$(F_* X)_q = dF_{F^{-1}(q)}(X_{F^{-1}(q)}) \text{ called the}$$

pushforward

Vector fields have a nice operation, called the

Lie Bracket  $[-, -]: \mathfrak{X}(M) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$

Defined by  $[X, Y]_f = XYf - YXF$

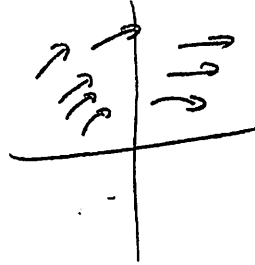
in coordinates,  $[X, Y] = \left( X^i \frac{\partial Y^j}{\partial x^i} - Y^i \frac{\partial X^j}{\partial x^i} \right) \frac{\partial}{\partial x^j}$

Brackets respect F-relatedness, in particular, it

commutes with pushforward -  $F_*[X, Y] = [F_*X, F_*Y]$

## Flows

In  $\mathbb{R}^n$ , vector fields are like currents infinitesimally describe a motion



Taking infinitesimal steps in the direction of the vector field

Def: For a vector field  $V \in \mathcal{X}(M)$ , a curve  $\gamma: I \rightarrow M$  is an integral curve of  $V$  if

$\dot{\gamma}(t) = V_{\gamma(t)}$ .  $V$  is said to be the velocity vector field for  $\gamma$

In coordinates,  $\dot{\gamma}(t) = V_{\gamma(t)}$  becomes

$$\dot{\gamma}^i(t) \frac{\partial}{\partial x^i} = V^i(\gamma(t)) \frac{\partial}{\partial x^i}$$

Which is a system of ODE. We know how to solve these in  $\mathbb{R}^n$  (Existence + uniqueness thm)

and solving them is a local problem

$\Rightarrow$  We can do it on manifolds via charts

Thm: Given a smooth vector field  $V$ , for all  $p \in M$ ,  
 there exists an interval  $(-\epsilon, \epsilon)$  and a smooth  
 integral curve  $\gamma: (-\epsilon, \epsilon) \rightarrow M$  with  $\gamma(0) = p$

So given a vector field  $V$ , we can <sup>(usually)</sup> put these integral  
 curves together into a diffeomorphism.

Def: A global flow on  $M$  is a smooth map

$$\Theta: \mathbb{R} \times M \rightarrow M \quad \text{s.t.}$$

$$\begin{aligned} 1) \quad & \Theta(t, \Theta(s, p)) = \Theta(t+s, p) \\ & \Theta(0, p) = p. \end{aligned}$$

i.e. a group action  $\mathbb{R}^+ \curvearrowright M$ .

To end, Lie brackets?  
 Frobenius' theorem?

A flow determines maps in two ways

$$\begin{aligned} \Theta_+ : M &\rightarrow M \\ p &\mapsto \Theta(+, p) \end{aligned}$$

$$\begin{aligned} \Theta^{(p)} : \mathbb{R} &\rightarrow M \\ t &\mapsto \Theta(t, p) \end{aligned}$$

$\Theta^{(p)}$  gives a vector field

by differentiating  $V_p = \dot{\Theta}^{(p)}(0)$